
GDE

$$(\Delta + 2\Omega) * \frac{\partial^2 \mathbf{u}}{\partial \mathbf{x}^2} + \Omega \frac{\partial^2 \mathbf{u}}{\partial \mathbf{y}^2} + (\Delta + \Omega) * \frac{\partial^2 \mathbf{v}}{\partial \mathbf{x} \partial \mathbf{y}} - \frac{(\mathbf{x} + \mathbf{u}) * \lambda}{\sqrt{(\mathbf{x} + \mathbf{u})^2 + (\mathbf{r} + \mathbf{v})^2}} = 0;$$

$$(\Delta + 2\Omega) * \frac{\partial^2 \mathbf{v}}{\partial \mathbf{y}^2} + \Omega \frac{\partial^2 \mathbf{v}}{\partial \mathbf{x}^2} + (\Delta + \Omega) * \frac{\partial^2 \mathbf{u}}{\partial \mathbf{x} \partial \mathbf{y}} - \frac{(\mathbf{r} + \mathbf{v}) * \lambda}{\sqrt{(\mathbf{x} + \mathbf{u})^2 + (\mathbf{r} + \mathbf{v})^2}} = 0;$$

Flux Boundary Conditions

$$\Delta * \frac{\partial \mathbf{v}}{\partial \mathbf{y}} + (\Delta + 2\Omega) * \frac{\partial \mathbf{u}}{\partial \mathbf{x}} = 0;$$

$$\Omega * \left(\frac{\partial \mathbf{u}}{\partial \mathbf{y}} + \frac{\partial \mathbf{v}}{\partial \mathbf{x}} \right) = 0;$$

$$\Omega * \left(\frac{\partial^2 \mathbf{v}}{\partial \mathbf{y}^2} + \frac{\partial^2 \mathbf{v}}{\partial \mathbf{x}^2} \right) = 0;$$

$$\Delta * \frac{\partial \mathbf{v}}{\partial \mathbf{y}} + (\Delta + 2\Omega) * \frac{\partial \mathbf{u}}{\partial \mathbf{x}} = 0;$$

Inequality Boundary Condition

$$g = -\mathbf{r} + \sqrt{(\mathbf{r} + \mathbf{v})^2 + (\mathbf{u} + \mathbf{x})^2} \geq 0$$

\mathbf{u} and \mathbf{v} are displacement field which are functions of \mathbf{x} and \mathbf{y}

\mathbf{r} is a constant.

Ω and Δ are constants

λ is the lagrange multiplier used to impose the inequality constraint(g) while minimising the potential energy.